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Power Semiconductor Simulation

Final Report

March 30, 2001

Submitted by

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Abstract

This document describes the development of the Hydrodynamic Power Semiconductor Device Simulator (HPSDS), which solves the quantum mechanical hydrodynamic balance equations for the electrons and holes, along with the Poisson equation, for a two-dimensional device. The program will compute the electrostatic potential, electron and hole densities, recombination rate, electron and hole velocities, current densities, electron and hole temperature, and other quantities of interest as functions of applied bias. The program allows extensive analysis of unipolar, bipolar, and heterostructure devices. Power devices such as thyristor and other four or five terminal devices are treated under all possible operating conditions. Both steady state and transient operating conditions can be considered. Because of the inclusion of energy balance equations and heat diffusion equation, accurate high-field characteristics can be obtained with this program.

Silicon and Gallium Arsenide are the primary materials considered in this program, although other materials can be included if the user supply the necessary material data file. In particular, wide band-gap materials such as Silicon Carbide and Gallium Nitride are being currently added to the materials library of the code. All materials related parameters are contained within a single subroutine, so that it is easily modified by the user to suit his own situation. For the theoretical basis and numerical implementation of the code, the reader is directed to the references. Materials parameters are also discussed in the references.

1. Introduction

1.1 Scope

This document reports on the project entitled "Power Semiconductor Simulation". The following paragraphs will identify a software system for accurate and computationally efficient codes for simulating high-power semiconductor devices. The codes were developed for use in any parallel-processing environment, which has the Massage Passing Interface (MPI), a de-facto standard of parallel programming model.

1.2 Objectives

The goal of this project was to develop a working simulation package for power semiconductor devices, such as large area thyristors, and high frequency devices, such as MESFETs, HEMTs for use in oscillators. Aside from the traditional materials to be simulated such as silicon and gallium arsenide, wide band gap semiconductors like silicon carbide will be simulated because of its good thermal and high voltage properties. The simulation code will be based on scaleable hardware and will be rapidly accessible to DoD researchers.

The project of large-scale numerical simulation of semiconductor devices involves computational tasks that are too demanding for single stand-alone computers and workstations. These tasks are best tackled with massively parallel computers. The numerical codes developed in this project will be specially tailored to suit massively parallel machines.

The code will enable users to perform full electrical and thermal analysis of semiconductor devices under high power/voltage/current operating conditions, thus making it a very useful design and simulation tool for power semiconductor applications as well as applicable to self-heating device studies and temperature dependent model generation.

1.3 Approach

Modeling of power semiconductor devices is more challenging than the modeling of ordinary semiconductor devices in that the former involves not only charge transport but also thermal transport in the devices. Further, the conduction of electricity is coupled with the conduction of heat. Thus the modeling/simulation of power devices depends upon the solution of a set of coupled nonlinear partial differential equations, the Poisson equation, the current continuity equations, and the semiconductor transport equations, as well as the heat diffusion equation, subject to the appropriate initial and boundary, conditions. The task of solving such a complicated system of equations entails extremely high demand for computing resources, both in terms of CPU cycles and memory. Massively parallel hardware and corresponding software will be needed to accomplish such a task.

1.4 Major Program Elements

The package contains several functional blocks, each of which is designed to perform a certain task. Each block is made of many program units, which perform sub-tasks. The program units have one or more subroutines or functions. In addition, a library consisting of commonly used tools are attached, along with several modeling drivers. The code is written in FORTRAN-90 language.

The blocks are:

Control (CF),
Definitions (DF),
Discretization (DS),
Devices (DV),
Local Quantities (LC),
Materials Parameters (MT).

The following is a complete list of the program units in each functional block. All the units are coded in FORTRAN-90 at the present time.

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The blocks are:

Control (CT);
Definitions (DF);
Discretization (DS);
Devices (DV);
Local Quantities (LC);
Materials Parameters (MT).

The following is a complete list of the program units in each functional block. All the units are coded in FORTRAN 90 at the present time.

CT_ADT
CT_DF
CT_ENERG
CT_PARTI
CT_POISS
DF_ENERG
DF_MOMEN
DF_PARTI
DF_POISS
DS_CARRIER_DENSITY

DS CARRIER_TEMPR

DS CHEMICAL_POTENTIAL

DS CURRENT DENSITY

DS DOPEN DENSITY

DS ENERGY DENSITY

DS ENERGY_FLOW_DENSITY

DS ENERGY RATE

DS EQUI EQS

DS INVERSE_MASS

DS NPARA

DS_NPARA_CURRENT

DS NPARA_POTENTIAL

DS NPARA_TEMPR

DS PARTICLE RATE

DS PHASE_VELOCITY

DS POTENTIAL

DS SCAT RATE

DS VELOCITY RATE

DS VELOCITY_TENSOR

DV_1D

DV 2D

DV BOUND

DV_MyBOLISTIC_1D

GRĪD

HYSOLVER_UNITS

HyBE

LCEQ UNITS

LC CARRIER_DENSITY

LC CHEMPOT

LC CORR FUNC

LC CURRENT DENSITY

LC ENERGY DENSITY

LC ENERGY FLOW DENSITY

LC_ENERGY_RATE

LC EQUI EQS

LC INVERSE MASS

LC NPARA

LC NPARA CURRENT

LC NPARA POTENTIAL

LC NPARA_TEMPR

LC_PARTICLE_RATE

LC PHASE_VELOCITY

LC SCAT RATE

LC_SINGLE_LT

LC SINGLE LT IMP

LC SINGLE_LT_PH

LC VELOCITY_RATE

LC VELOCITY_TENSOR

 $\overline{MT}ADT$

MT AIGAAS

MT GENER

MT KANE

MT PARAB

MT_USER

WKSPACE

LIB ELEMFUN

LIB_IE_POLATION

LIB INTG

LIB INTG GAUSS

LIB MATRIX

LIB N CONST

LIB P CONST

LIB ROOT

LIB VECP

2. Major Tasks

The following is a list of major tasks with the above observation in mind.

- 1. Parallelization of existing code for ballistic diode.
- 2. Single particle, time-independent code implemented
- 3. Modification of code to p-n diode and then power diode.
- 4. Single particle, time independent code parallelized
- 5. Single particle, time dependent code implemented
- 6. Modification of code for multilayer devices
- 7. Many-body, time independent code implemented8. Single particle, time dependent code parallelized
- 9. Interface code development
- 10. Many-body, time independent code parallelized
- 11. Many-body, time-dependent code implemented
- 12. Single particle, time dependent, full band structure code implemented
- 13. Many-body, time dependent code parallelized.

3. Major Accomplishments

Schedule of Events

The following schedule reflects the schedule and status of the major tasks outlined above.

Module/Tasks	Expected Completion	Actual Completion	
task 1	1/97	1/97	
task 2	3/97	3/97	
task 3	7/97	7/97	

task 4	10/97	10/97	
task 5	12/97	12/97	
task 6	3/98	3/98	
task 7	6/98	4/98	
task 8	6/98	6/98	
task 9	9/98	8/98	
task 10	12/98	12/98	
task 11	5/99	3/99	
task 12	12/99	3/00	
task 13	12/99	5/00	

5. Alpha test summary

The following is a summary of the milestones and metrics demonstrated at the off-site CEN-2 Alpha testing conducted at Wright-Patterson AFB, on April 14, 1998.

- 63% speed-up achieved with 16 processors.
- MPI used on SGI Origin 2000 and SGI-PCA supercomputers.
- Now in process of moving parallel code to IBM SP-2.
- Reasonable load balance achieved.

Objective	Required	Observed
Scaled Speedup (16 nodes)	40 %	63%
% code in high level	80 %	100 %
language		
Number of HPC platforms	2	2
software will run on.		
# of validations per week	4 or more	4
User computer expertise	Required = 2 (no GUI)	2
required.(1-10)	1=GUI, 5= need to modify	
	source code each run.	
Major error & % fixable per	10, 80 %	5, 100%
week.		
% Of software allows for	User specifies input and	User specifies input and
interactive processing.	waits for output in a non	waits for output in a non
	real-time mode.	real-time mode.
# of validations on full code	1 per 2 months	1 per 2 months
% of required external code	Greater or equal to 60%	60 %
interfaces completed	•	
% Of last validations that	60 %	100 %
were accurate and valid.		
# Of potential users exposed	Greater or equal to 10	10
to new software capability		
through problems solved for		

.4	
them.	
	,

The parameters that can be calculated by computation method are summarized in the next table:

Carrier density	Yes
Carrier temperature	Yes
Electrostatic potential	Yes
Electric field	Yes
Current and current density	Yes

All outputs currently viewed with third party graphics visualization software.

6. Beta Test Results

Objective (CTP)		Beta Test
Scaled Speedup	REQ	50% on 32 processors
	OBS	
Scaled Speedup	REQ	Reduces clock time 16x or > on 32 processors
	OBS	
% code uses standard	REQ	90% or >
higher order languages, etc	OBS	
Number of HPC platforms software will run on with	REQ	2
valid results.	OBS	
4 or more validation testes on full code/month	REQ	Yes
	OBS	
Levels of users expertise software provides.	REQ	1
	OBS	
# major errors or < each week and % fixable	REQ	2, 100% within 2 workdays
	OBS	
# data/sets/user scenarios tested/week	REQ	4 or more
	OBS	
% of possible useful output parameters provided	REQ	90%
	OBS	

% of required external code interfaces completed	REQ	80% or greater
	OBS	
% of last 10 software runs produced accurate, valid	REQ	80%
output	OBS	
# of new users added to CTA's HPC community over	REQ	15 or more
last year.	OBS	

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